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针对多视角数据缺失问题,本文提出一种基于视角相容性的补全方法,该方法通过共享子空间的监督学习,建立视角相容性判别模型.基于共享子空间重构误差等同分布假设,提出了针对视角缺失的多视角数据的共享表征方法,在此基础上,通过进一步的多元线性回归,实现多视角数据缺失的精确补全.

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